



# Reasoning in the Situation Calculus with Limited Belief

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**Classical** logic:

- Unrealistic: omniscient agent
- Undecidable (*first-order*) / intractable (*propositional*)

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**Task:** Robot has a KB and a query:

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**Limited belief:** [Lakemeyer & Levesque, KR-2016]

- Belief level 0: explicit beliefs KB + unit propagation + subsumption
- Belief level  $k + 1$ : implicit beliefs belief level  $k$  + one case split

Hypothesis: good results at *small* belief level

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- ▶ First-order quantification
- ▶ Introspective belief
- ▶ Conditional belief
- ▶ Actions ← this paper

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- ▶ Sudoku: level 0  $\approx$  easy; 1  $\approx$  medium; 2  $\approx$  hard; 4  $\approx$  extreme



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- ▶ Sudoku: level 0  $\approx$  easy; 1  $\approx$  medium; 2  $\approx$  hard; 4  $\approx$  extreme
- ▶ Minesweeper: level 0 is bad; 1 is good; 2 slightly better; 3 same

- Logical language for actions, sensing, knowledge
- Values of functions / predicates change in **situations**
- Situation is a **sequence of actions**
- **Basic action theory:**
  - ▶ successor-state axioms **capture effects of actions**
  - ▶ sensing axiom **captures how knowledge is produced**
  - ▶ initial theory **describes the initial state**
- **Projection:** does a BAT entail a query after certain actions?

# The Language

**FOL** with equality + functions + sorts +

- Knowledge:  $\mathbf{K}_0\alpha$   $\mathbf{K}_1\alpha$   $\mathbf{K}_2\alpha$  ...
- Possibility:  $\mathbf{M}_0\alpha$   $\mathbf{M}_1\alpha$   $\mathbf{M}_2\alpha$  ...
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- ▶  $[\text{birth}(\text{Mia}, \text{Sally})] \mathbf{K}_1 \text{fatherOf}(\text{Sally}) = \text{spouseOf}(\text{motherOf}(\text{Sally}))$

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- ▶  $[\text{birth}(\text{Mia}, \text{Sally})] [\text{test}(\text{Mia}, \text{Fred})] \mathbf{K}_1 \text{fatherOf}(\text{Sally}) = \text{Frank}$



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standard names represent distinct individuals

# The Semantics

**Model:** set of possible worlds

**Belief:** true in all possible worlds

# The Semantics

disjunction of literals  $[A_1] \dots [A_j](\neg)t_1 = t_2$

**Model:** set of **clauses** closed under unit propagation

- Belief level 0: subsumption
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**Example:**

If we know that (a)  $\text{spouseOf}(\text{Mia}) = \text{Frank} \vee \text{spouseOf}(\text{Mia}) = \text{Fred}$

and (b)  $\text{motherOf}(\text{Sally}) = \text{Mia}$

and (c)  $\text{motherOf}(y) \neq z \vee \text{spouseOf}(z) \neq x \vee \text{fatherOf}(y) = x$

then  $\mathbf{K}_0(\text{fatherOf}(\text{Sally}) = \text{Frank} \vee \text{fatherOf}(\text{Sally}) = \text{Fred}) ?$

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**No!** No known clause subsumes  $\text{fatherOf}(\text{Sally}) = \text{Frank} \vee \text{fatherOf}(\text{Sally}) = \text{Fred}$ .

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and (c)  $\text{motherOf}(y) \neq z \vee \text{spouseOf}(z) \neq x \vee \text{fatherOf}(y) = x$

then  $\mathbf{K}_1(\text{fatherOf}(\text{Sally}) = \text{Frank} \vee \text{fatherOf}(\text{Sally}) = \text{Fred}) ?$

**Yes!** Branch on  $\text{spouseOf}(\text{Mia})$ :

- ▶  $\{(a), (b), (c), \text{spouseOf}(\text{Mia}) = \text{Frank}\} \ni \text{fatherOf}(\text{Sally}) = \text{Frank}$  by UP with (b), (c)
- ▶  $\{(a), (b), (c), \text{spouseOf}(\text{Mia}) = \text{Fred}\} \ni \text{fatherOf}(\text{Sally}) = \text{Fred}$  by UP with (b), (c)
- ▶  $\{(a), (b), (c), \text{spouseOf}(\text{Mia}) = n\} \ni \perp$  by UP with (a)  
for  $n \neq \text{Frank}, \text{Fred}$

## Proper<sup>+</sup> Knowledge Bases

Let KB be a conjunction of clauses

$$\forall \vec{x} (l_1 \vee \dots \vee l_j)$$

$$\square \forall \vec{x} (l_1 \vee \dots \vee l_j)$$

where  $l_i$  is of the form  $[A_1] \dots [A_l](\neg)t_1 = t_2$

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## Theorem: Soundness

KB entails query at a belief level  $\implies$  KB entails query classically



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## Theorem: Eventual Completeness

If KB and query contain no  $\exists, \forall, \square$ :

KB entails query classically  $\implies$  KB entails query at a belief level

## Basic Action Theories

Contains successor-state axioms

$$\Box([a]f(x_1, \dots, x_j) = y \equiv \phi_f)$$

And a sensed-fluent axiom

$$\Box(\text{sf}(a) = y \equiv \psi)$$

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**Example:**

$$\Box([a]\text{motherOf}(x) = y \equiv a = \text{birth}(y, x) \vee \\ a \neq \text{birth}(y, x) \wedge \text{motherOf}(x) = y)$$

$$\Box([a]\text{fatherOf}(x) = y \equiv \exists \hat{y} (a = \text{birth}(\hat{y}, x) \wedge \text{spouseOf}(\hat{y}) = y) \vee \\ \forall \hat{y} (a \neq \text{birth}(\hat{y}, x) \wedge \text{fatherOf}(x) = y))$$

$$\Box(\text{sf}(a) = y \equiv \exists x \exists \hat{y} (a = \text{test}(\hat{y}, x) \wedge \text{fatherOf}(x) = \hat{y}) \wedge y = \text{Yes} \vee \\ \forall x \forall \hat{y} (a \neq \text{test}(\hat{y}, x) \vee \text{fatherOf}(x) \neq \hat{y}) \wedge y = \text{No})$$

$$\text{spouseOf}(\text{Mia}) = \text{Frank} \vee \text{spouseOf}(\text{Mia}) = \text{Fred}$$

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If KB is a BAT translated into proper<sup>+</sup> form, and query is  $\Box$ -free:  
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### Theorem: Tractability

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KB entails query at a belief level **is tractable**

# Regression

Eliminates actions:

1. Push actions  $[A]$  inwards

2. **Functions:** axioms relate truth **after** and **before**  $A$

$$[A]f(t_1, \dots, t_j) = t_{j+1} \mapsto \Phi_f^{a \ x_1 \dots x_j \ y} A \ t_1 \dots t_j \ t_{j+1}$$

3. **Knowledge:** theorems relate knowledge **after** and **before**  $A$

$$[A]\mathbf{K}_k \alpha \mapsto \forall x (\text{sf}(A) = x \supset \mathbf{K}_k(\text{sf}(A) = x \supset [A]\alpha))$$

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# Summary

*still work in progress*

**Limbo** implements limited belief and actions

Demos: [www.cse.unsw.edu.au/~cschwering/limbo](http://www.cse.unsw.edu.au/~cschwering/limbo)

Code: [www.github.com/schwering/limbo](https://www.github.com/schwering/limbo)

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- More expressivity e.g., progression
- Clause learning

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Practical challenges:

- Keep up with the theory
- Improve performance
- Find applications

## Appendix

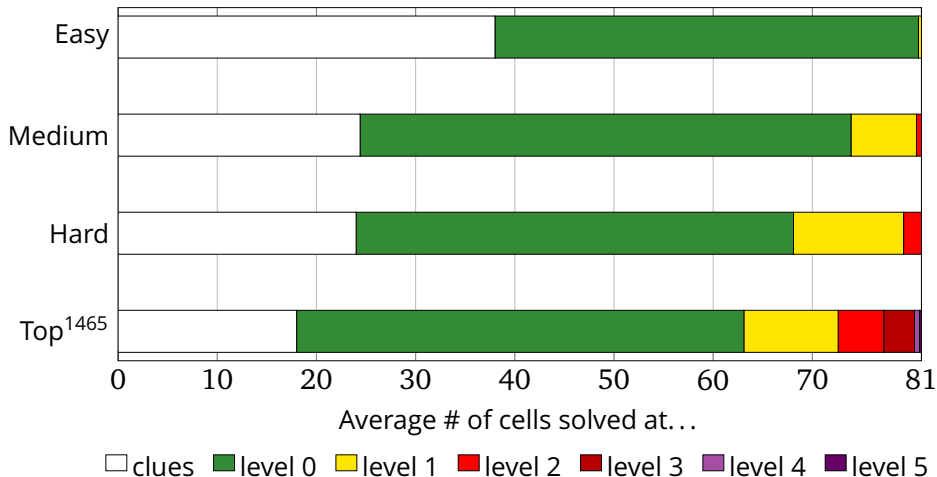
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